# GRI-PHI |

## PIEZOELECTRIC MICROGRIPPERS

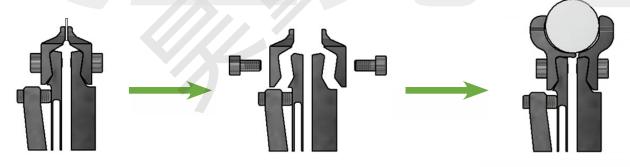


### **Features**

- Sample size to be manipulated: from 10 µm up to more then 20 mm
- More then 40 mln cycles
- Customizable jaws
- Fast actuation: up to tens of hz
- Proportional opening
- Programmable opening cycles
- Fixed or removable jaws
  - Customizable shape and performance
  - Dedicated electronics and software available

### **Applications**

- Microlens manipulation and positioning
- Fiber optic sensors assembly
- Precision mounting on assembly chain
- Micro-contacts and electronics manipulation





From very small specimen

Same body, jaws substitution

3

To specimens of different shapes and dimensions

Phi Drive's grippers can be used for accurate and fast assembly of microcomponents in automatic process. Available in 3 different options, can be mounted on PHI-W the PhiDrive's robotic wrist.

## 5 D.O.F.s

#### **GRIPPERS ROBOT WRIST**

#### **Features**

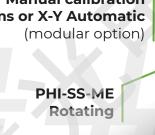
- From 2 up to 5 D.O.F. s available (2 rotations and 3 translations)
- **Light** and **compact**: h152, Ø58 mm
- Closed-loop control available
- **Very high** resolution: up to nanoradiants and micronmetres
- Easy-to-use PC interface

### **Applications**

- Optics
- Photonics
- Micromanipulation
- Microelectronics
- Mounting and positioning
- Assembly chain

**Tilting stage** (±5°) PHI-SS-TS

X-Y Manual calibration systems or X-Y Automatic





Increase robot precision

The piezoelectric stages combined in their DOFs make it possible to align optics, manipulate electronic components, mount micro-contacts in the production chain.

precision and accurately grab even

the smallest samples.

**Z** Calibration system (possible automatic implementation)

Griphi

Microgripper

in micromanipulation





